

# Memory Kernel and CP-Divisibility of Gaussian Collisional Models<sup>1</sup>

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## Collisional Model

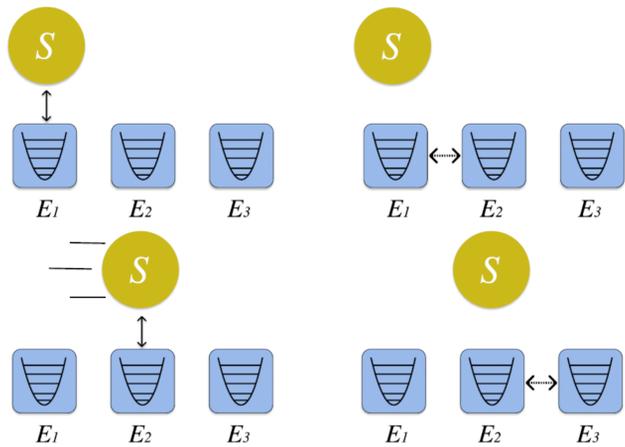


FIG. 1. First steps of the studied non-Markovian collisional model.

We consider the figure's initially uncorrelated collisional model where the system-ancilla interactions  $SE_n$  are interspersed by ancilla-ancilla interactions  $E_nE_{n+1}$  under two gaussian Hamiltonians: beam splitter BS and two-mode squeezing TMS. Setting  $SE_n$  as BS interaction while allowing  $E_nE_{n+1}$  to be either, we study the memory effects generated by the dynamics. As the global evolution of  $SE_1E_2\dots$  is unitary, we can translate into symplectic form for the total covariance matrix  $\sigma$ :

$$\sigma^n = S_{n,n+1} S_n \sigma^{n-1} S_n^T S_{n,n+1}^T$$

where  $S_n$  and  $S_{n,n+1}$  are the symplectic matrices associated with the unitaries  $SE_n$  and  $E_nE_{n+1}$  correspondingly.

## Markovian Embedding:

The resulting dynamics at any time involves only  $SE_nE_{n+1}$ . Ancillas with  $m \geq n+2$  did not participate yet and the ancillas with  $m < n$  will never participate again. Therefore, we define the reduced CM of  $SE_{n+1}$

$$\gamma^n = \begin{pmatrix} \theta^n & \xi_{n+1}^n \\ \xi_{n+1}^{n,T} & \epsilon_{n+1}^n \end{pmatrix},$$

where  $\theta^n$  is the system's CM;  $\epsilon^n$ , the ancilla's; and  $\xi^n$ , the correlation between them. Eq. (1) can be cast as

$$\gamma^{n+1} = X\gamma^n X^T + Y,$$

where  $X, Y$  are 4 by 4 matrices referring to the unitaries. We plot the BS and TMS maps where  $\lambda_s$  refers to the  $SE_n$  interaction strength, and  $\lambda_e, \nu_e$  to the  $E_nE_{n+1}$ .

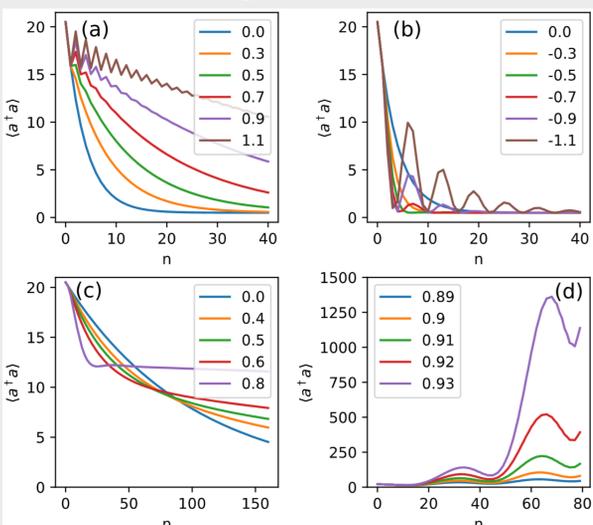


FIG. 2. Number of excitations in the system as a function of time. (a,b) BS dynamics with  $\lambda_s = 0.5$  and different values of  $\lambda_e$  (with  $\lambda_e > 0$  in (a) and  $\lambda_e < 0$  in (b)). (c,d) Same, but for the TMS dynamics, with  $\lambda_s = 0.1$  and different values of  $\nu_e$  (with  $\nu_e < \nu_e^{\text{crit}}$  in (a)  $\nu_e \geq \nu_e^{\text{crit}}$  in (b), where  $\nu_e^{\text{crit}} = \sinh^{-1}(1) \approx 0.8813$ ). The ancillas start in the vacuum, and the system in a thermal state with  $\langle a^\dagger a \rangle^0 = 20$ .

## Memory Kernel

A much older notion of non-Markovianity is that of a memory kernel  $\mathcal{K}_{t-t'}$ , as present already in the seminal works of Nakajima and Zwanzig

$$\frac{d\rho_S}{dt} = -i[H_S, \rho_S] + \int_0^t \mathcal{K}_{t-t'}[\rho(t')] dt'$$

Within our framework, one may equivalently formulate a memory kernel acting only on the system's covariance matrix  $\theta$ . This can be accomplished by writing down the difference equation for the system's only:

$$\theta^{n+1} = x^2 \theta^n + \sum_{r=0}^{n-1} \mathcal{K}_{n-r-1}(\theta^r) + G_n$$

We can write more explicitly in terms of a Kraus operator-sum representation:

$$\mathcal{K}_n(\theta) = \sum_{ij} k_{ij}^n M_i \theta M_j^T$$

where  $k_{ij}^n$  are coefficients that depend on time and  $\{M_i\}$  are a complete 2 by 2 set of matrices  $\{\mathbb{I}_2, \sigma_z, \sigma_+, \sigma_-\}$ .

The memory itself is contained in the dependence of  $k_{ij}^n$  on  $n$ . The subscripts  $i, j$  determines how different elements of  $\theta^r$  affect  $\theta^n$ . For instance, in the BS map, the only non-zero coefficient will be the one proportional to  $\mathbb{I}_2 \theta \mathbb{I}_2$  which we refer to as  $k_{11}^n$ , i.e.  $\mathcal{K}_n(\theta) = k_{11}^n \theta$ .

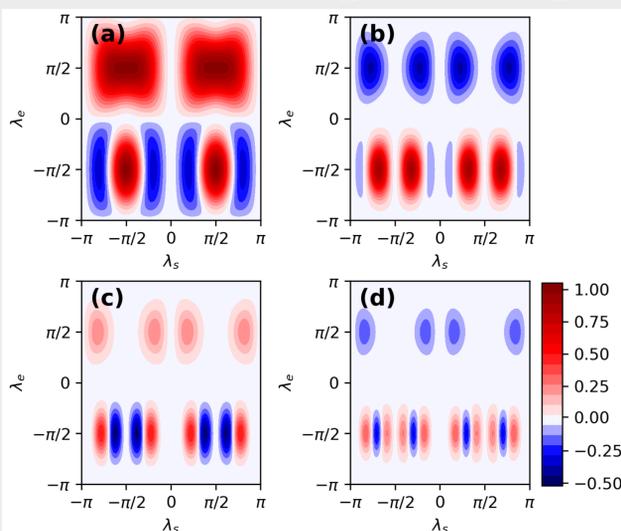


FIG. 3. Diagrams for the memory kernel coefficient  $k_{11}^n$  in the  $(\lambda_s, \lambda_e)$  plane for different values of  $n$ , from  $n=0$  to  $n=4$

Conversely, in the TMS map there will be four non-zero coefficients  $k_{11}^n, k_{1,z}^n, k_{z,1}^n$  and  $k_{z,z}^n$ , corresponding to  $\mathbb{I}_2$  and  $\sigma_z$ . We plot the memory kernels of  $Q^2$  and  $P^2$   $k_q^n = k_{11}^n + k_{1,z}^n + k_{z,1}^n + k_{z,z}^n$  and  $k_p^n = k_{11}^n - k_{1,z}^n - k_{z,1}^n + k_{z,z}^n$

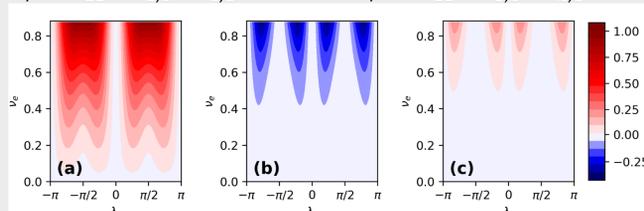


FIG. 4. Diagrams for the memory kernel coefficient  $k_q$  of the TMS dynamics in the  $(\lambda_s, \nu_e)$  plane for  $n=0$  to  $n=2$

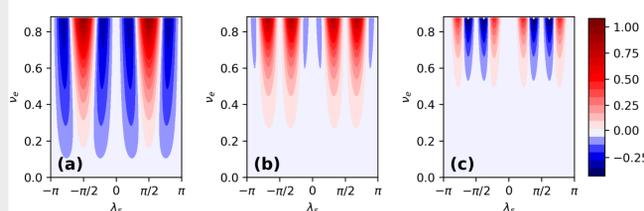


FIG. 5. Diagrams for the memory kernel coefficient  $k_p$  of the TMS dynamics in the  $(\lambda_s, \nu_e)$  plane for  $n=0$  to  $n=2$

## CP-Divisibility

Map divisibility is the ultimate test of non-Markovianity. For Gaussian dynamics, any CPTP map must have the form  $\theta \rightarrow \mathcal{X}\theta\mathcal{X}^T + \mathcal{Y}$  where the matrices satisfies

$$\mathcal{M}[\mathcal{X}, \mathcal{Y}] := 2\mathcal{Y} + i\Omega - i\mathcal{X}\Omega\mathcal{X}^T \geq 0$$

with  $\Omega = i\sigma_y$  the symplectic form.

In our case, the evolution of the system from initial time 0 to step  $n$  has the form

$$\theta^n = \mathcal{X}_n \theta^0 \mathcal{X}_n^T + \mathcal{Y}_n$$

The matrices  $\mathcal{X}_n$  and  $\mathcal{Y}_n$  can be read from the (1,1) block of the general solution

$$\mathcal{X}_n = (X^n)_{11},$$

$$\mathcal{Y}_n = (X^n)_{12} \epsilon (X^n)_{12}^T + \sum_{r=0}^{n-1} \left[ X^{n-r-1} Y (X^T)^{n-r-1} \right]_{11}$$

To probe whether the dynamics is divisible, we consider the mapping taking the system from  $n$  to  $m$  ( $m > n$ )

$$\theta^m = \mathcal{X}_{mn} \theta^n \mathcal{X}_{mn}^T + \mathcal{Y}_{mn}$$

where

$$\mathcal{X}_{mn} = \mathcal{X}_m \mathcal{X}_n^{-1}, \quad \mathcal{Y}_{mn} = \mathcal{Y}_m - \mathcal{X}_{mn} \mathcal{Y}_n \mathcal{X}_{mn}^T$$

The dynamics is then considered divisible when the intermediate maps are CPTP, that is  $\mathcal{M}[\mathcal{X}_{mn}, \mathcal{Y}_{mn}] \geq 0$ . The above criteria can be also used as a figure of merit

$$\mathcal{N}_{mn} = \sum_k \frac{|m_k| - m_k}{2}$$

where  $m_k = \text{eigs}(\mathcal{M}[\mathcal{X}_{mn}, \mathcal{Y}_{mn}])$

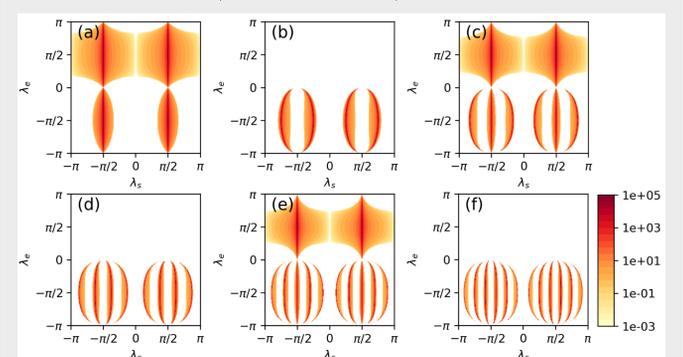


FIG. 6. CP-Divisibility measure  $\mathcal{N}_{n+1,n}$  in the  $(\lambda_s, \lambda_e)$  plane for the BS dynamics. Each plot corresponds to a different value of  $n$  from 1 to 6 in steps of 1.

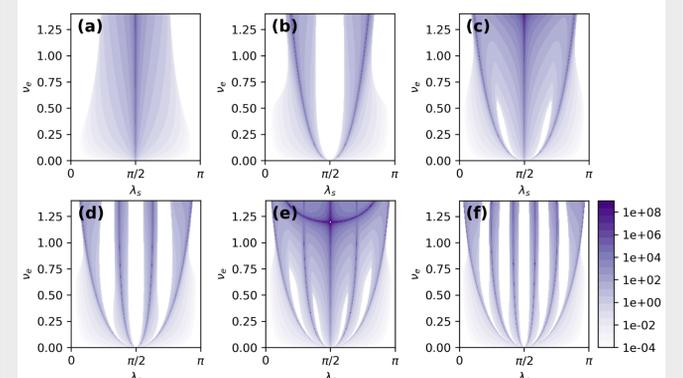


FIG. 7. CP-Divisibility measure  $\mathcal{N}_{n+1,n}$  in the  $(\lambda_s, \nu_e)$  plane for the TMS dynamics. Each plot corresponds to a different value of  $n$  from 1 to 6 in steps of 1.

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## References

<sup>1</sup>R. R. Camasca and G. T. Landi, Memory kernel and divisibility of gaussian collisional models, arXiv preprint arXiv:2008.00765 (2020).